Utility of Computerized Isocentric Fluoroscopy for Minimally Invasive Spinal Surgical Techniques

Alan T. Villavicencio, MD,* Sigita Burneikiene, MD,* Ketan R. Bulsara, MD,† and Jeffrey J. Thramann, MD*

Objective: The purpose of this study was to prospectively evaluate the clinical utility and accuracy of intraoperative three-dimensional fluoroscopy as an adjunct for the placement of a complex spinal instrumentation.

Methods: The Siemens Iso-C three-dimensional fluoroscopy unit in the combination with the Stealth Treon computer volumetric navigational system was used. A total of 279 spinal instrumentation screws or transpedicular cannulations were performed in 69 patients. Accuracy, operative time, and amount of fluoroscopy utilization time were assessed for transformaminar lumbar interbody fusion (TLIF) and kyphoplasty cases.

Results: Only 4 percutaneous transpedicular lumbar screws out of 265 total (1.5%) were malpositioned. Average operative time for TLIF cases was 185 minutes (range 114–311 minutes) for one-level and 292.6 minutes (range 173–390 minutes) for two-level procedures. Biplanar fluoroscopy utilization time was 93 seconds (range 27–280 seconds) for one-level procedures and 216 seconds (range 80–388 seconds) for two-level procedures. Average surgery duration for kyphoplasty was 60 minutes (range 36–79 minutes) for one-level procedures and 68.5 minutes (range 65–75 minutes) for two-level cases. Biplanar fluoroscopy utilization time was 41.3 seconds per case (range 25–62 seconds).

Conclusions: Use of intraoperative three-dimensional fluoroscopy for image guidance in minimally invasive complex spinal instrumentation procedures is feasible and safe. This technique provides excellent visualization of three-dimensional relationships. This potentially results in improved accuracy of screw positioning and the ability to detect misplaced screws prior to wound closure. This technique also potentially results in a significant reduction in radiation exposure for both the patient and the staff.

Key Words: 3-D fluoroscopy, image guidance, iso-C, spine surgery (J Spinal Disord Tech 2005;18:369–375)

Reduced visualization of the operative field in minimally invasive surgery requires higher accuracy. The unreliability of the routine two-dimensional fluoroscopy in assessing pedicle screw placement has been previously demonstrated. Based on these studies, the rate of penetration of the pedicle cortex by an inserted screw ranges from 5% to 41% for open lumbar spine cases.1–8 Weinstein et al9 revealed limitations of two-dimensional fluoroscopy in an in vitro study. They reported a 21% incidence of pedicle screw malpositioning, 92% of perforations being medial. This was confirmed in clinical studies. Castro et al10 revealed 40% misplacement, 71.4% perforations being medial. Introduction of image guidance technology has significantly altered previously mentioned rates. These vary from 0% to 9%.5,10–14 Unfortunately, computed tomography (CT)-based surgical navigation requires time-consuming intraoperative point-to-point registration steps and preoperative planning that introduces an inherent amount of error into the system.

Standard intraoperative fluoroscopy lacks the ability to reconstruct three-dimensional images. There are no axial images available intraoperatively, frequently resulting in the need to constantly reposition the C-arm and take more frequent images, with increased radiation exposure. These drawbacks associated with conventional fluoroscopy have led to the development of Iso-C fluoroscopy units such as the Siremobil Iso-C three-dimensional fluoroscopy (Siemens Medical Solutions, Erlangen, Germany), which allows acquisition of axial, sagittal, and coronal images and produce three-dimensional reconstructions. This prospective, nonrandomized cohort study evaluates the feasibility and accuracy of using intraoperative three-dimensional fluoroscopic guidance for placement of hardware in complex spinal procedures.

MATERIALS AND METHODS

Placement of 265 spinal instrumentation screws and 14 transpedicular kyphoplasty procedures were performed using Iso-C three-dimensional fluoroscopic navigation between July 2003 and September 2004. Forty-five patients (63.4%) were female and twenty-four (36.6%) were male. Average age of the patients was 55.2 years (range 19–99 years).

Patient data, including preoperative and postoperative evaluations, were collected on a prospective basis. Thirty-six patients (52.2%) underwent interbody fusion with percutaneous pedicle screws for discogenic pain. Fifteen patients were treated for spinal fractures: Eleven patients (15.9%) were treated with kyphoplasty procedures for pathologic compression-type fractures, three patients (4.3%) were treated
for type II odontoid fractures, and one patient (1.5%) was treated with C2 pedicle screws and C3 lateral mass screws. Eighteen patients (26.1%) underwent surgery for spinal instability. Patients with discogenic pain were selected for surgery based on a history of mechanical symptoms and failed conservative treatment.

Biplanar fluoroscopy exposure time and operative time were assessed for transforaminal lumbar interbody fusion (TLIF) and kyphoplasty procedures. Accuracy of screw placement was evaluated on intraoperative Iso-C fluoroscopy images (Fig. 1) and verified on thin-slice (1- to 1.5-mm) postoperative helical CT scans (Fig. 2A-B). Because of the small numbers, statistical analysis was not performed for other procedures such as Magerl and odontoid screws, cervical lateral mass, or C2 pedicle screw placement.

Any penetration of the screw was measured in millimeters using the CT scan image scale. A four-group classification was used: 0–2, 2–4, 4–6, and 6–8 mm. Localization of the violation was also noted.

Fine-cut postoperative helical CT scans were obtained postoperatively to evaluate the accuracy of the image guidance (see Fig. 3). This included confirming the position of the implants for instrumentation cases and assessing the path of the trocar and position of bone cement for kyphoplasty cases.

Surgical Procedures

Two hundred twenty percutaneous pedicle screws were placed in 46 patients undergoing TLIF. Twenty-eight patients (60.9%) underwent surgery for a single level: 12 (42.8%) at L5–S1, 10 (35.7%) at L4–L5, 4 (14.3%) at L3–L4, 1 (3.6%) at L1–L2, and 1 patient (3.6%) at L2–L3. Eighteen patients (39.1%) had surgery on two levels: 15 (83.3%) at L4–L5 and L5–S1, 2 (11.1%) at L3–L4 and L4–L5, and 1 patient (5.6%) at L2–L3 and L3–L4.

Eleven patients with pathologic compression fractures underwent percutaneous kyphoplasty procedures. Eight patients (72.7%) had a single fractured level, whereas three patients (27.3%) had vertebral fractures at two levels. Ten patients
(90.9%) had primary osteoporotic vertebral compression, and one (9.1%) was treated for osteolytic metastatic disease. Three lumbar (L1–L5) and 11 thoracic (T4–T12) kyphoplasty procedures were performed.

C2 odontoid screws were placed in three patients with type II odontoid fractures. Two patients with atlantoaxial instability had C1–C2 transarticular (Magerl) screws placed. Three patients underwent subaxial cervical lateral mass fixation performed on three, four, and six levels, respectively. A total of 32 subaxial cervical lateral mass screws were placed. Two patients had C1 lateral mass fixation (four screws) and two patients had C2 pedicle screws (four screws). Table 1 summarizes the total number of screws placed.

**Technique**

After localization of the appropriate levels with standard fluoroscopy using the Iso-C unit, a dynamic reference array was attached to an adjacent-level spinous process for registration. No surgeon-dependent registration step was required. The registration process is automated. The Siemens Iso-C three-dimensional fluoroscopy unit acquires intraoperative images while the C-arm is rotating in the angular and orbital directions, with the center focus precisely maintained. There is no need to adjust the unit when switching between anterior-posterior and lateral views. The C-arm functions concurrently as a regular fluoroscopy unit, while also allowing for the three-dimensional reconstruction of images into axial, sagittal, and coronal planes (Figs. 4 and 5) by acquiring 100 two-dimensional images through an Iso-C 190° rotation. Reconstructed three-dimensional volumes of 256 isotropic pixel images are transferred to the Stealth Station Treon Treatment Guidance System (Medtronic, Louisville, CO). An integrated navigation interface NaviLink was used for direct connection to navigation systems. It took approximately 2 minutes to acquire the images and another 60 seconds for the three-dimensional reconstructions.

All pedicle screws were inserted using Iso-C fluoroscopy image guidance. Standard two-dimensional fluoroscopy was used to localize the appropriate spinal levels for pedicle screw placement (see Fig. 6, A and B) and in kyphoplasty procedures prior to placement of the dynamic reference array.

### TABLE 1. Surgical Procedures and Misplaced Screw Rates

<table>
<thead>
<tr>
<th>Procedure</th>
<th>Levels</th>
<th>Patients</th>
<th>Screws</th>
<th>Misplaced</th>
</tr>
</thead>
<tbody>
<tr>
<td>One-level TLIF</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>L5–S1</td>
<td>12</td>
<td>48</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>L4–L5</td>
<td>10</td>
<td>40</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>L3–L4</td>
<td>4</td>
<td>16</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>L1–L2</td>
<td>1</td>
<td>4</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>L2–L3</td>
<td>1</td>
<td>4</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>Total</td>
<td>28</td>
<td>112</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>Two-level TLIF</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>L4–L5, L5–S1</td>
<td>15</td>
<td>90</td>
<td>3 (3.3%)</td>
<td></td>
</tr>
<tr>
<td>L3–L4, L4–L5</td>
<td>2</td>
<td>12</td>
<td>1 (8.3%)</td>
<td></td>
</tr>
<tr>
<td>L2–L3, L3–L4</td>
<td>1</td>
<td>6</td>
<td>None</td>
<td></td>
</tr>
<tr>
<td>Total</td>
<td>18</td>
<td>108</td>
<td>4 (3.7%)</td>
<td></td>
</tr>
<tr>
<td>Odontoid screws</td>
<td>C2</td>
<td>3</td>
<td>3</td>
<td>None</td>
</tr>
<tr>
<td>C1–C2 Magerl screws</td>
<td>C1–C2</td>
<td>2</td>
<td>2</td>
<td>None</td>
</tr>
<tr>
<td>Subaxial cervical lateral mass screws</td>
<td>C1–C7</td>
<td>3</td>
<td>32</td>
<td>None</td>
</tr>
<tr>
<td>C2 pedicle screws</td>
<td>C2</td>
<td>2</td>
<td>4</td>
<td>None</td>
</tr>
<tr>
<td>C1 lateral mass screws</td>
<td>C1</td>
<td>2</td>
<td>4</td>
<td>None</td>
</tr>
<tr>
<td>Total</td>
<td>58</td>
<td>265</td>
<td>4 (1.5%)</td>
<td></td>
</tr>
</tbody>
</table>

**RESULTS**

**Operative Data and Biplanar Fluoroscopy Time**

Average operative time for one-level procedures was 185 minutes (range 114–311 minutes) and 292.6 minutes (range 173–390 minutes) for two-level percutaneous TLIF procedures. Average duration of surgery for one-level kyphoplasty procedures was 60 minutes (range 36–79 minutes) and for two-level cases 68.5 minutes (range 65–75 minutes) (Table 2).

Average biplanar fluoroscopy utilization time (see Table 2) with Iso-C fluoroscopy-assisted cases was 93 seconds (range 27–280 seconds) for one-level TLIF procedures and 216 seconds (range 80–388 seconds) for two-level TLIF procedures. For kyphoplasty procedures, this averaged 41.3 seconds per case (range 25–62 seconds). There was another 40 seconds of fluoroscopy time during the initial “spin” and the intraoperative “spin” to verify good screw placement.
Accuracy Assessment and Complications

There were no misplaced screws in the odontoid, C1–C2, Magerl, lateral mass, C2 pedicle screw, or one-level TLIF patient groups. All pedicles were cannulated without difficulty in the percutaneous kyphoplasty group. Four patients (1.5%) had misplaced pedicle screws in the two-level minimally invasive TLIF group. One patient had 6-mm (grade III) medial pedicle screw perforation at L5 and underwent reoperation for removal of the screw 1 day after the original surgery. In this case, a postoperative verification “spin” was not performed. Another patient had 5-mm lateral perforation (grade III) at L4, which was identified by a second Iso-C fluoroscopy “spin” intraoperatively, and the screw was repositioned accordingly. For two patients, a slight cortical breach (grade I) was identified intraoperatively, but it was elected to leave pedicle screws in place based on the size of the pedicles and because there was <2 mm of lateral perforation (see Table 1). These findings as well as screw placement within the cortical margins were confirmed by the postoperative helical CT scans.

Other complications included postoperative hematomas in 2 of 69 patients (2.9%); 2 patients were treated for new postoperative radiculopathy (2.9%). Two patients had postoperative numbness and dorsiflexion weakness that resolved within 3 months of surgery. One patient (1.4%) developed a seroma 10 days after the surgery, which was negative to any bacterial pathogens. Lumbar paraspinal fluid aspiration was performed. One patient with severe cervical spondylotic myelopathy died 3 days following surgery as a result of severe coronary artery disease and acute renal failure.

DISCUSSION

Conventional techniques for placement of pedicle screws are based primarily on intraoperative anatomic landmarks and preoperative imaging studies. However, anatomic landmarks vary considerably not only among different individuals with
normal spinal anatomy, but especially in patients with scoliosis, degenerative spondylolisthesis, and osteoarthritis where variable transformations in the facet joint and pedicle axis orientation are present. Image guidance technologies bring the surgeon closer to the ideal starting point and trajectory, therefore increasing accuracy. With the recent development of minimally invasive surgical techniques, where anatomic landmarks cannot be visualized, image guidance is essential.

The inability to obtain axial and sagittal reconstructed images remains the main limitation of using conventional fluoroscopy for intraoperative image guidance. This increases the potential for pedicle screw violation and neural injury. Theoretically, repeated fluoroscopic images need to be taken to verify instrument or implant position, which increases radiation exposure to the patient and operative room personnel. Repositioning and adjusting the C-arm during the surgical procedure to obtain adequate views can be cumbersome, and it can be difficult to maintain sterility. Although CT and magnetic resonance imaging have the capacity to obtain axial images, neither of these imaging modalities is suitable for routine use in the operating room.

Iso-C fluoroscopy employs axial, coronal, and sagittal reconstructed images, real-time navigation, automated registration, and intraoperative postinstrumentation evaluation. These intraoperative “verification of screw placement images” often eliminate the need for the follow-up radiologic examination and ensure proper placement of instrumentation prior to the patient leaving the operating room.

**Accuracy**

In a recent clinical study, a 1.7% pedicle screw misplacement rate was reported using isocentric fluoroscopy. Our reported incidence of 1.5% is consistent with this. In addition, all screw malpositions in this series occurred during the first 16 cases and the initial 3 months of using Iso-C fluoroscopy for intraoperative image guidance. A 0% rate of misplaced screws in the lumbar and 8% in the thoracic spine were reported in experimental settings where percutaneous misplaced screws in the lumbar and 8% in the thoracic spine were reported in experimental settings. However, violations of the cortical bone can weaken biomechanical construct, even if they are asymptomatic.

Hott et al evaluated Iso-C fluoroscopy data and its concurrence with postoperative CT studies. Six percent (2/33) of the screws violated the margin of the pedicle wall by <2 mm and were successfully identified in intraoperative Iso-C fluoroscopic evaluation. Wang et al compared the reliability of conventional CT and three-dimensional fluoroscopy in a human cadaver spine model for assessing pedicle violations. Iso-C fluoroscopy was slightly more sensitive but less specific than conventional CT scans; 28.4% of pedicle violations were not detected, and 21.1% were incorrectly determined as misplaced. Higher-grade violations (>4 mm) were detected 100% of the time with Iso-C fluoroscopy. In our study, we performed Iso-C fluoroscopy immediately at the end of the surgery followed by postoperative helical CT scans for verification of accuracy. Three cases of pedicle screw misplacement were identified correctly, and one was not recognized using Iso-C fluoroscopy and required reoperation. This is related to the fact that a second “verification” spin was not performed in this case. If this had been performed, it is likely that the cortical breach would have been identified and corrected, thus saving the patient a second trip to the operating room.

The calculated accuracy rate of pedicle screw placement using Iso-C three-dimensional fluoroscopy in our study was 98.5%, which favorably compares with the previously reported results. A definite learning curve was observed, in which all reported complications occurred during the first 16 cases and the initial 3 months of use.

Registration of most types of the existing navigational devices is based on anatomic landmarks. The greatest degree of inaccuracy in the procedure is added by the registration process. The registration process using Iso-C fluoroscopy navigation is automated. No manual registration is involved. By eliminating this requirement, a higher degree of accuracy is theoretically achieved. Choi et al measured the root mean square registration accuracy for Iso-C fluoroscopy in the clinical setting, which averaged 1.1 mm (range 0.8–2.3 mm). According to Rampersaud et al, the highest degree of accuracy is required at the midcervical, midthoracic, and thoracolumbar junction regions, with a translational error of <1 mm and rotational error of <5°.

**Radiation Exposure**

The Iso-C three-dimensional fluoroscopy unit acquires intraoperative images while the C-arm is rotating in the angular and orbital directions, with the center focus precisely maintained. This design eliminates the need to readjust the C-arm’s horizontal or vertical travel when changing between anteroposterior and lateral positions. Thus, positioning is quick and easy, potentially saving time. Although Iso-C three-dimensional fluoroscopy does not completely eliminate the subsequent need for conventional fluoroscopic images, its overall effect is to decrease the amount of radiation exposure to both the patient and the operating room personnel, while at the
same time provide improved image guidance. The dose associated with the initial 2-minute “spin” for Iso-C fluoroscopy is 0.75 times lower than for standard two-dimensional fluoroscopy, therefore a 120-second “spin” is equivalent to 30 seconds of standard two-dimensional fluoroscopy. The surgical team does not even have to be in the same room as the patient during the acquisition phase of the image guidance process. In addition to the 40 seconds of fixed radiation time during 120 seconds of intraoperative “spin,”25,29 93 seconds of biplanar fluoroscopy time was used on average for one-level TLIF, 216 seconds for two-level TLIF, and 41 seconds for kyphoplasty procedures. Choi et al (unpublished data, 2003) reported 66 seconds’ average (range 30–126 seconds) of fluoroscopy time for pedicle screw placement in lumbar, thoracic, and cervical spine. Fifty-eight pedicles in 14 consecutive patients were instrumented at the University of Colorado Hospital using this technique. Two patients with cervical, 1 with thoracic, and 11 with lumbar pathologies were included in this series. Grutzner et al17 used 88 ± 56 seconds of fluoroscopy time for 302 pedicle screws placed in 61 patients (4.9 screws per patient).

The main limitation of our study was that it was nonrandomized and we did not have a control group to compare operative data and biplanar fluoroscopy time for the cases where Iso-C image guidance was not used. Gebhard et al compared the dose of radiation exposure for surgical procedures performed with and without image guidance using CT-based navigation, conventional C-arm navigation, and Iso-C navigation. The lowest emission of ionizing radiation was for the Iso-C method. Average fluoroscopy times were reported for the different procedures: 180 seconds for conventional fluoroscopy, 79 seconds for CT-based navigation, 91 seconds for C-arm-based navigation, and 20 seconds for Iso-C-based navigation.

Operative Time

Foley et al30 reported 240 minutes’ average operative time for minimally invasive TLIF cases using biplanar fluoroscopy, which would compare with 238.8 minutes’ average time for all cases or 185 minutes’ time for one-level and 292.6 minutes for two-level cases in this study. The average operative duration using intraoperative three-dimensional navigation reported by Grutzner et al17 was 103.26 ± 23.3 minutes. Three hundred two pedicle screws were placed in 61 patients (4.9 screws per patient). No information was given on what kind of screws was used or whether this was the total time per surgery or just screw placement.

Limitations

Image quality is directly related to the amount of artifact generated by any type of metal in the field of view, including any metallic implants.24 Image quality could potentially be suboptimal for obese patients, and it has been reported that some morbidly obese patients do not fit into the C-arm.24,25 In our experience, we have not encountered either of these problems. Another potential limitation involves the fact that the image volume during the spin is limited to about four spinal levels, depending on the size of the patient. Additional “spins” might therefore be occasionally required for long constructs.25

CONCLUSION

This study demonstrates that use of Iso-C three-dimensional fluoroscopy for intraoperative image guidance in minimally invasive complex spinal instrumentation procedures is feasible and safe. Based on our rates of malpositioned screws, this technique seems to provide improved visualization over the standard fluoroscopy of three-dimensional relationships, which results in an increased accuracy of screw positioning and the potential to detect misplaced screws prior to wound closure. This technique also seems to result in a reduction of radiation exposure. We believe that these advantages justify the increased cost of acquiring the equipment. Further randomized comparison with conventionally used fluoroscopy systems would be needed to more critically evaluate the improved accuracy of this technique.

REFERENCES